6ES7288-1SR60-0AA1

Data sheet



SIMATIC S7-200 SMART, CPU SR60, CPU, AC/DC/relay, onboard I/O: 36 DI 24 V DC; 24 DQ relay 2 A; power supply: AC 85 - 264 V AC at 47-63 Hz program/data memory 50 KB web server support

General information	
Product type designation	CPU SR60 AC/DC/Relay
Engineering with	
 Programming package 	STEP 7 Micro/WIN SMART
Installation type/mounting	
Rail mounting	Yes; Standard - DIN rail
Supply voltage	
Rated value (AC)	
• 120 V AC	Yes
• 230 V AC	Yes
permissible range, lower limit (AC)	85 V
permissible range, upper limit (AC)	264 V
Line frequency	
 permissible range, lower limit 	47 Hz
 permissible range, upper limit 	63 Hz
Input current	
Current consumption (rated value)	220 mA; at 240 V AC
Current consumption, max.	370 mA; At 120 V AC
Inrush current, max.	16.3 A; at 264 V
Output current	
Current output, max.	300 mA; 24 V DC Sensor Power
for backplane bus (5 V DC), max.	1.4 A; max. 5 V DC for EM bus
Power loss	
Power loss, max.	25 W
Memory	
Type of memory	DDR
Flash	Yes
RAM	Yes
Memory available for user data	20 kbyte
Memory size	30 kbyte; Program memory
Micro Memory Card	Yes; microSDHC Card (optional)
Backup	
• present	Yes; Maintenance free, RTC requires 7 days.
CPU processing times	
for bit operations, typ.	150 ns; / instruction
for word operations, typ.	1.2 μs; / instruction
for floating point arithmetic, typ.	3.6 µs; / instruction
Address area	
I/O address area	
• Inputs	144 byte; 256 bit of digital inputs & 56 words of analog inputs

Outputs	144 byte; 256 bit of digital outputs & 56 words of analog outputs
Time of day	
Clock	
• Type	Hardware clock, no battery backup
Hardware clock (real-time)	Yes
Backup time	7 d
Deviation per day, max.	120 s; within 120s/month at 25 °C
Digital inputs	120 0, William 1200 months at 20 0
Number of digital inputs	36; Integrated
of which inputs usable for technological functions	4; HSC (High Speed Counting)
Source/sink input	Yes
Number of simultaneously controllable inputs	165
all mounting positions	
* .	26
— up to 40 °C, max.	36
Input voltage	P0
Type of input voltage	DC
Rated value (DC)	24 V
• for signal "0"	5 V DC at 1 mA
• for signal "1"	15 V DC at 2.5 mA
Input current	
• for signal "0", max. (permissible quiescent current)	1 mA
• for signal "1", typ.	4 mA
Input delay (for rated value of input voltage)	
for standard inputs	
— parameterizable	Yes; 0.2 ms, 0.4 ms, 0.8 ms, 1.6 ms, 3.2 ms, 6.4 ms and 12.8 ms, selectable in
at 11011 to 11411 pain	groups of four
— at "0" to "1", min.	0.2 ms
— at "0" to "1", max.	12.8 ms
for interrupt inputs	
— parameterizable	Yes
for technological functions	
— parameterizable	Yes; 6 Single phase: 4 HSCs at 200 kHz; 2 HSCs at 30 kHz 4 A/B phase: 2 HSCs at 100 kHz; 2 HSCs at 20 kHz
Cable length	TIOGO AT 100 MIL, L'ITOGO AT LO MIL
• shielded, max.	500 m; 50 m for technological functions
unshielded, max. unshielded, max.	300 m; for technological functions: No
Digital outputs	300 m, for technological functions. No
	OA Delevie
Number of digital outputs	24; Relays
Switching capacity of the outputs	
with resistive load, max.	2 A
on lamp load, max.	30 W; 30 W with DC, 200 W with AC
Output delay with resistive load	
• "0" to "1", max.	10 ms; max.
● "1" to "0", max.	10 ms; max.
Switching frequency	
 of the pulse outputs, with resistive load, max. 	1 Hz
Relay outputs	
Number of relay outputs	24
Cable length	
• shielded, max.	500 m
• unshielded, max.	150 m
Interfaces	
Number of industrial Ethernet interfaces	1
Number of RS 485 interfaces	1
1. Interface	
Interface type	PROFINET
Isolated	Yes; Transformer isolated, 1,500V AC
automatic detection of transmission rate	Yes; 10/100 Mbit/s
	Yes Yes
Autoregoing	
Autocrossing	Yes
Interface types	

RJ 45 (Ethernet)	Yes
Protocols	, 30
PROFINET IO Controller	Yes; Since V2.4
PROFINET IO Device	Yes; I-Device since V2.5
PROFINET IO Controller	
Transmission rate, max.	100 Mbit/s
Services	
 Number of connectable IO Devices, max. 	8
Updating time	4 ms; The minimum value of the update time also depends on the
	communication component set for PROFINET IO, on the number of IO devices and the quantity of configured user data.
Address area	, ,
— Inputs, max.	128 byte; Per device
— Outputs, max.	128 byte; Per device
2. Interface	
Interface type	RS 485 (max. 187.5 kbps)
Interface types	
• RS 485	Yes
PROFIBUS DP master	
Services	
— S7 communication	Yes
Protocols	
Supports protocol for PROFINET IO	Yes; RT Controller (since FW V2.4) & I-Device (since FW V2.5)
PROFIBUS	Yes; Via CM DP module
Protocols (Ethernet)	Vee
• TCP/IP	Yes
communication functions / header	
S7 communication	Yes
supported as server	Yes
as client	Yes
Test commissioning functions	
Test commissioning functions Status/control	
	Yes
Status/control	Yes
Status/control • Status/control variable	Yes
Status/control • Status/control variable Forcing	
Status/control • Status/control variable Forcing • Forcing	Yes; PID closed-loop control function: Continuous controller outputs, binary
Status/control • Status/control variable Forcing • Forcing Integrated Functions PID controller	Yes
Status/control • Status/control variable Forcing • Forcing Integrated Functions	Yes; PID closed-loop control function: Continuous controller outputs, binary controller outputs, automatic/manual mode, max. 8 loops
Status/control • Status/control variable Forcing • Forcing Integrated Functions PID controller Number of pulse outputs	Yes; PID closed-loop control function: Continuous controller outputs, binary controller outputs, automatic/manual mode, max. 8 loops
Status/control Status/control variable Forcing Forcing Integrated Functions PID controller Number of pulse outputs Potential separation	Yes; PID closed-loop control function: Continuous controller outputs, binary controller outputs, automatic/manual mode, max. 8 loops
Status/control • Status/control variable Forcing • Forcing Integrated Functions PID controller Number of pulse outputs Potential separation Potential separation digital inputs	Yes; PID closed-loop control function: Continuous controller outputs, binary controller outputs, automatic/manual mode, max. 8 loops 3
Status/control • Status/control variable Forcing • Forcing Integrated Functions PID controller Number of pulse outputs Potential separation Potential separation digital inputs • between the channels, in groups of	Yes; PID closed-loop control function: Continuous controller outputs, binary controller outputs, automatic/manual mode, max. 8 loops 3
Status/control Status/control variable Forcing Forcing Integrated Functions PID controller Number of pulse outputs Potential separation Potential separation digital inputs between the channels, in groups of Potential separation digital outputs	Yes; PID closed-loop control function: Continuous controller outputs, binary controller outputs, automatic/manual mode, max. 8 loops 3
Status/control Status/control variable Forcing Forcing Integrated Functions PID controller Number of pulse outputs Potential separation Potential separation digital inputs between the channels, in groups of Potential separation digital outputs between the channels	Yes; PID closed-loop control function: Continuous controller outputs, binary controller outputs, automatic/manual mode, max. 8 loops 3
Status/control Status/control variable Forcing Forcing Integrated Functions PID controller Number of pulse outputs Potential separation Potential separation digital inputs between the channels, in groups of Potential separation digital outputs between the channels between the channels between the channels, in groups of	Yes; PID closed-loop control function: Continuous controller outputs, binary controller outputs, automatic/manual mode, max. 8 loops 3
Status/control Status/control variable Forcing Forcing Integrated Functions PID controller Number of pulse outputs Potential separation Potential separation digital inputs between the channels, in groups of Potential separation digital outputs between the channels between the channels between the channels between the channels, in groups of	Yes; PID closed-loop control function: Continuous controller outputs, binary controller outputs, automatic/manual mode, max. 8 loops 3
Status/control Status/control variable Forcing Forcing Integrated Functions PID controller Number of pulse outputs Potential separation Potential separation digital inputs between the channels, in groups of Potential separation digital outputs between the channels between the channels between the channels hetween the channels discharge of static electricity Interference immunity against discharge of static	Yes; PID closed-loop control function: Continuous controller outputs, binary controller outputs, automatic/manual mode, max. 8 loops 1 No 2
Status/control Status/control variable Forcing Forcing Integrated Functions PID controller Number of pulse outputs Potential separation Potential separation digital inputs between the channels, in groups of Potential separation digital outputs between the channels between the channels between the channels between the channels between the channels of EMC Interference immunity against discharge of static electricity Interference immunity against discharge of static electricity acc. to IEC 61000-4-2	Yes; PID closed-loop control function: Continuous controller outputs, binary controller outputs, automatic/manual mode, max. 8 loops 1 No 2 Yes
Status/control Status/control variable Forcing Forcing Integrated Functions PID controller Number of pulse outputs Potential separation Potential separation digital inputs between the channels, in groups of Potential separation digital outputs between the channels between the channels, in groups of EMC Interference immunity against discharge of static electricity Interference immunity against discharge of static electricity acc. to IEC 61000-4-2 — Test voltage at air discharge	Yes; PID closed-loop control function: Continuous controller outputs, binary controller outputs, automatic/manual mode, max. 8 loops 1 No 2 Yes 8 kV 4 kV
Status/control Status/control variable Forcing Forcing Integrated Functions PID controller Number of pulse outputs Potential separation Potential separation digital inputs between the channels, in groups of Potential separation digital outputs between the channels, in groups of Potential separation digital outputs between the channels between the channels between the channels, in groups of EMC Interference immunity against discharge of static electricity Interference immunity against discharge of static electricity acc. to IEC 61000-4-2 — Test voltage at air discharge — Test voltage at contact discharge	Yes; PID closed-loop control function: Continuous controller outputs, binary controller outputs, automatic/manual mode, max. 8 loops 1 No 2 Yes 8 kV 4 kV
Status/control Status/control variable Forcing Forcing Integrated Functions PID controller Number of pulse outputs Potential separation Potential separation digital inputs between the channels, in groups of Potential separation digital outputs between the channels, in groups of Potential separation digital outputs between the channels between the channels between the channels, in groups of EMC Interference immunity against discharge of static electricity Interference immunity against discharge of static electricity acc. to IEC 61000-4-2 — Test voltage at air discharge — Test voltage at contact discharge Interference immunity against high-frequency electromagnetic field Interference immunity against high-frequency radiation	Yes; PID closed-loop control function: Continuous controller outputs, binary controller outputs, automatic/manual mode, max. 8 loops 1 No 2 Yes 8 kV 4 kV s Yes; 10 V/m, 80 to 1 000 MHz (to IEC 61000-4-3); 10 V/m, 900 MHz, 1.89 GHz,
Status/control Status/control variable Forcing Forcing Forcing Integrated Functions PID controller Number of pulse outputs Potential separation Potential separation digital inputs between the channels, in groups of Potential separation digital outputs between the channels between the channels between the channels, in groups of EMC Interference immunity against discharge of static electricity Interference immunity against discharge of static electricity acc. to IEC 61000-4-2 — Test voltage at air discharge Test voltage at contact discharge Interference immunity against high-frequency electromagnetic field Interference immunity against high-frequency radiation acc. to IEC 61000-4-3	Yes; PID closed-loop control function: Continuous controller outputs, binary controller outputs, automatic/manual mode, max. 8 loops 1 No 2 Yes 8 kV 4 kV s Yes; 10 V/m, 80 to 1 000 MHz (to IEC 61000-4-3); 10 V/m, 900 MHz, 1.89 GHz,
Status/control Status/control variable Forcing Forcing Integrated Functions PID controller Number of pulse outputs Potential separation Potential separation digital inputs between the channels, in groups of Potential separation digital outputs between the channels between the channels, in groups of Potential separation digital outputs between the channels between the channels between the channels, in groups of EMC Interference immunity against discharge of static electricity Interference immunity against discharge of static electricity ac. to IEC 61000-4-2 — Test voltage at air discharge Test voltage at contact discharge Interference immunity against high-frequency electromagnetic field Interference immunity against high-frequency radiation acc. to IEC 61000-4-3 Interference immunity to cable-borne interference Interference immunity on supply lines acc. to IEC 61000-	Yes; PID closed-loop control function: Continuous controller outputs, binary controller outputs, automatic/manual mode, max. 8 loops 1 No 2 Yes 8 kV 4 kV s Yes; 10 V/m, 80 to 1 000 MHz (to IEC 61000-4-3); 10 V/m, 900 MHz, 1.89 GHz, 50% ED (to IEC 61000-4-3)
Status/control Status/control variable Forcing Forcing Integrated Functions PID controller Number of pulse outputs Potential separation Potential separation digital inputs between the channels, in groups of Potential separation digital outputs between the channels between the channels between the channels between the channels therference immunity against discharge of static electricity Interference immunity against discharge of static electricity Interference immunity against discharge Test voltage at air discharge Test voltage at contact discharge Interference immunity against high-frequency electromagnetic field Interference immunity against high-frequency radiation acc. to IEC 61000-4-3 Interference immunity to cable-borne interference Interference immunity on supply lines acc. to IEC 61000-4-4 Interference immunity on signal cables acc. to IEC 61000-4-4	Yes; PID closed-loop control function: Continuous controller outputs, binary controller outputs, automatic/manual mode, max. 8 loops 1 No 2 Yes 8 kV 4 kV s Yes; 10 V/m, 80 to 1 000 MHz (to IEC 61000-4-3); 10 V/m, 900 MHz, 1.89 GHz, 50% ED (to IEC 61000-4-3) Yes; 2 kV acc. to IEC 61000-4-4, burst Yes; ±2 kV acc. to IEC 61000-4-4, Burst
Status/control Status/control variable Forcing Forcing Integrated Functions PID controller Number of pulse outputs Potential separation Potential separation digital inputs • between the channels, in groups of Potential separation digital outputs • between the channels • brown the channels • between the channels discharge of static electricity • Interference immunity against discharge of static electricity acc. to IEC 61000-4-2 — Test voltage at air discharge — Test voltage at contact discharge Interference immunity against high-frequency electromagnetic field • Interference immunity against high-frequency radiation acc. to IEC 61000-4-3 Interference immunity to cable-borne interference • Interference immunity on supply lines acc. to IEC 61000-4-4 • Interference immunity on signal cables acc. to IEC 61000-4-4	Yes; PID closed-loop control function: Continuous controller outputs, binary controller outputs, automatic/manual mode, max. 8 loops 1 No 2 Yes 8 kV 4 kV s Yes; 10 V/m, 80 to 1 000 MHz (to IEC 61000-4-3); 10 V/m, 900 MHz, 1.89 GHz, 50% ED (to IEC 61000-4-3) Yes; 2 kV acc. to IEC 61000-4-4, burst Yes; ±2 kV acc. to IEC 61000-4-4, Burst

Emission of radio interference acc. to EN 55 011	
Limit class A, for use in industrial areas	Yes; EN 61000-6-4, interference emission: Intended for use in industrial areas.
Emission of conducted and non-conducted interference	
Interference emission via line/AC current cables	EN 61000-6-4, interference emission: Intended for use in industrial areas.
Standards, approvals, certificates	
CE mark	Yes
Ambient conditions	
Free fall	
Fall height, max.	0.3 m; five times, in product package
Ambient temperature during operation	
• min.	-20 °C
• max.	60 °C
 horizontal installation, min. 	-20 °C
 horizontal installation, max. 	60 °C
 vertical installation, min. 	-20 °C
 vertical installation, max. 	55 °C
Ambient temperature during storage/transportation	
• min.	-40 °C
• max.	70 °C
Air pressure acc. to IEC 60068-2-13	
 Storage/transport, min. 	660 hPa
Storage/transport, max.	1 080 hPa
Altitude during operation relating to sea level	
 Installation altitude, min. 	-1 000 m
 Installation altitude, max. 	2 000 m
Relative humidity	
 Operation at 25 °C without condensation, max. 	95 %
configuration / header	
configuration / programming / header	
Programming language	
— LAD	Yes
— FBD	Yes
— STL	Yes
Dimensions	
Width	175 mm
Height	100 mm
Depth	81 mm
Weights	
Weight, approx.	611.5 g
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9/2/2021

last modified: