SIEMENS

Data sheet

6ES7212-1AE40-0XB0



SIMATIC S7-1200, CPU 1212C, compact CPU, DC/DC/DC, onboard I/O: 8 DI 24 V DC; 6 DO 24 V DC; 2 AI 0-10 V DC, Power supply: DC 20.4-28.8V DC, Program/data memory 75 KB

CPU 1212C DC/DC/DC
V4.4
STEP 7 V16 or higher
Yes
20.4 V
28.8 V
Yes
24 V
20.4 V
28.8 V
400 mA; CPU only
1 200 mA; CPU with all expansion modules
12 A; at 28.8 V DC
0.5 A ² ·s
1 000 mA; Max. 5 V DC for SM and CM
L+ minus 4 V DC min.
9 W
75 kbyte
No
2 Mbyte
with SIMATIC memory card
Yes
Yes

without battery	Yes
CPU processing times	
for bit operations, typ.	0.08 μs; / instruction
for word operations, typ.	1.7 µs; / instruction
for floating point arithmetic, typ.	2.3 µs; / instruction
CPU-blocks	2.5 μ5, / ποτιαστίστ
	DDs ECs EDs soundars and timeses. The requireum number of
Number of blocks (total)	DBs, FCs, FBs, counters and timers. The maximum number of addressable blocks ranges from 1 to 65535. There is no restriction, the entire working memory can be used
OB	
Number, max.	Limited only by RAM for code
Data areas and their retentivity	
Retentive data area (incl. timers, counters, flags), max.	10 kbyte
Flag	
• Size, max.	4 kbyte; Size of bit memory address area
Local data	
• per priority class, max.	16 kbyte; Priority class 1 (program cycle): 16 KB, priority class 2 to 26: 6 KB
Address area	
Process image	
Inputs, adjustable	1 kbyte
Outputs, adjustable	1 kbyte
Hardware configuration	
Number of modules per system, max.	3 comm. modules, 1 signal board, 2 signal modules
Time of day	
Clock	
Hardware clock (real-time)	Yes
Backup time	480 h; Typical
·	
Deviation per day, max.	±60 s/month at 25 °C
Digital inputs	
Number of digital inputs	8; Integrated
of which inputs usable for technological functions	6; HSC (High Speed Counting)
Source/sink input	Yes
Number of simultaneously controllable inputs	
all mounting positions	
— up to 40 °C, max.	8
Input voltage	
Rated value (DC)	24 V
• for signal "0"	5 V DC at 1 mA
• for signal "1"	15 V DC at 2.5 mA
Input delay (for rated value of input voltage)	
for standard inputs	
— parameterizable	0.2 ms, 0.4 ms, 0.8 ms, 1.6 ms, 3.2 ms, 6.4 ms and 12.8 ms, selectable in groups of four
— at "0" to "1", min.	0.2 ms
— at "0" to "1", max.	12.8 ms
for interrupt inputs	
— parameterizable	Yes
for technological functions	
— parameterizable	Single phase: 3 @ 100 kHz & 3 @ 30 kHz, differential: 3 @ 80 kHz & 3 @ 30 kHz
Cable length	
• shielded, max.	500 m; 50 m for technological functions
unshielded, max.	300 m; for technological functions: No
Digital outputs	
Number of digital outputs	6
of which high-speed outputs	4; 100 kHz Pulse Train Output
Limitation of inductive shutdown voltage to	L+ (-48 V)
	_ (')

Switching capacity of the outputs	
with resistive load, max.	0.5 A
• on lamp load, max.	5 W
Output voltage	
for signal "0", max.	0.1 V; with 10 kOhm load
● for signal "1", min.	20 V
Output current	
for signal "1" rated value	0.5 A
for signal "0" residual current, max.	0.1 mA
Output delay with resistive load	
• "0" to "1", max.	1 µs
• "1" to "0", max.	5 µs
Switching frequency	
of the pulse outputs, with resistive load, max.	100 kHz
Relay outputs	
Number of relay outputs	0
Cable length	
• shielded, max.	500 m
unshielded, max. unshielded, max.	150 m
Analog inputs	
7 1	2
Number of analog inputs	2
Input ranges	v
• Voltage	Yes
Input ranges (rated values), voltages	
• 0 to +10 V	Yes
— Input resistance (0 to 10 V)	≥100k ohms
Cable length	
shielded, max.	100 m; twisted and shielded
Analog outputs	
Number of analog outputs	0
	0
Analog value generation for the inputs	0
Analog value generation for the inputs Integration and conversion time/resolution per channel	
Analog value generation for the inputs Integration and conversion time/resolution per channel Resolution with overrange (bit including sign), max.	10 bit
Analog value generation for the inputs Integration and conversion time/resolution per channel Resolution with overrange (bit including sign), max. Integration time, parameterizable	10 bit Yes
Analog value generation for the inputs Integration and conversion time/resolution per channel Resolution with overrange (bit including sign), max. Integration time, parameterizable Conversion time (per channel)	10 bit
Analog value generation for the inputs Integration and conversion time/resolution per channel • Resolution with overrange (bit including sign), max. • Integration time, parameterizable • Conversion time (per channel) Encoder	10 bit Yes
Analog value generation for the inputs Integration and conversion time/resolution per channel Resolution with overrange (bit including sign), max. Integration time, parameterizable Conversion time (per channel) Encoder Connectable encoders	10 bit Yes 625 μs
Analog value generation for the inputs Integration and conversion time/resolution per channel Resolution with overrange (bit including sign), max. Integration time, parameterizable Conversion time (per channel) Encoder Connectable encoders 2-wire sensor	10 bit Yes
Analog value generation for the inputs Integration and conversion time/resolution per channel Resolution with overrange (bit including sign), max. Integration time, parameterizable Conversion time (per channel) Encoder Connectable encoders	10 bit Yes 625 μs
Analog value generation for the inputs Integration and conversion time/resolution per channel Resolution with overrange (bit including sign), max. Integration time, parameterizable Conversion time (per channel) Encoder Connectable encoders 2-wire sensor	10 bit Yes 625 μs
Analog value generation for the inputs Integration and conversion time/resolution per channel • Resolution with overrange (bit including sign), max. • Integration time, parameterizable • Conversion time (per channel) Encoder Connectable encoders • 2-wire sensor 1. Interface	10 bit Yes 625 μs Yes
Analog value generation for the inputs Integration and conversion time/resolution per channel • Resolution with overrange (bit including sign), max. • Integration time, parameterizable • Conversion time (per channel) Encoder Connectable encoders • 2-wire sensor 1. Interface Isolated	10 bit Yes 625 μs Yes
Analog value generation for the inputs Integration and conversion time/resolution per channel • Resolution with overrange (bit including sign), max. • Integration time, parameterizable • Conversion time (per channel) Encoder Connectable encoders • 2-wire sensor 1. Interface Isolated automatic detection of transmission rate	10 bit Yes 625 μs Yes Yes
Analog value generation for the inputs Integration and conversion time/resolution per channel • Resolution with overrange (bit including sign), max. • Integration time, parameterizable • Conversion time (per channel) Encoder Connectable encoders • 2-wire sensor 1. Interface Isolated automatic detection of transmission rate Autonegotiation	10 bit Yes 625 μs Yes Yes Yes Yes Yes
Analog value generation for the inputs Integration and conversion time/resolution per channel • Resolution with overrange (bit including sign), max. • Integration time, parameterizable • Conversion time (per channel) Encoder Connectable encoders • 2-wire sensor 1. Interface Isolated automatic detection of transmission rate Autonegotiation Autocrossing	10 bit Yes 625 μs Yes Yes Yes Yes Yes
Analog value generation for the inputs Integration and conversion time/resolution per channel • Resolution with overrange (bit including sign), max. • Integration time, parameterizable • Conversion time (per channel) Encoder Connectable encoders • 2-wire sensor 1. Interface Isolated automatic detection of transmission rate Autonegotiation Autocrossing Interface types	10 bit Yes 625 μs Yes Yes Yes Yes Yes Yes Yes
Analog value generation for the inputs Integration and conversion time/resolution per channel Resolution with overrange (bit including sign), max. Integration time, parameterizable Conversion time (per channel) Encoder Connectable encoders 2-wire sensor Interface Isolated automatic detection of transmission rate Autonegotiation Autocrossing Interface types RJ 45 (Ethernet)	10 bit Yes 625 μs Yes Yes Yes Yes Yes Yes Yes Y
Analog value generation for the inputs Integration and conversion time/resolution per channel Resolution with overrange (bit including sign), max. Integration time, parameterizable Conversion time (per channel) Encoder Connectable encoders 2-wire sensor Interface Isolated automatic detection of transmission rate Autonegotiation Autocrossing Interface types RJ 45 (Ethernet) Number of ports	10 bit Yes 625 μs Yes Yes Yes Yes Yes Yes Yes Y
Analog value generation for the inputs Integration and conversion time/resolution per channel Resolution with overrange (bit including sign), max. Integration time, parameterizable Conversion time (per channel) Encoder Connectable encoders 2-wire sensor 1. Interface Isolated automatic detection of transmission rate Autonegotiation Autocrossing Interface types RJ 45 (Ethernet) Number of ports integrated switch	10 bit Yes 625 μs Yes Yes Yes Yes Yes Yes Yes Y
Analog value generation for the inputs Integration and conversion time/resolution per channel Resolution with overrange (bit including sign), max. Integration time, parameterizable Conversion time (per channel) Encoder Connectable encoders 2-wire sensor Interface Isolated automatic detection of transmission rate Autonegotiation Autocrossing Interface types RJ 45 (Ethernet) Number of ports integrated switch Protocols	10 bit Yes 625 μs Yes Yes Yes Yes Yes Yes Yes Y
Analog value generation for the inputs Integration and conversion time/resolution per channel Resolution with overrange (bit including sign), max. Integration time, parameterizable Conversion time (per channel) Encoder Connectable encoders 2-wire sensor Interface Isolated automatic detection of transmission rate Autonegotiation Autocrossing Interface types RJ 45 (Ethernet) Number of ports integrated switch Protocols PROFINET IO Controller	10 bit Yes 625 μs Yes Yes Yes Yes Yes Yes Yes Y
Analog value generation for the inputs Integration and conversion time/resolution per channel Resolution with overrange (bit including sign), max. Integration time, parameterizable Conversion time (per channel) Encoder Connectable encoders 2-wire sensor Interface Isolated automatic detection of transmission rate Autonegotiation Autocrossing Interface types RJ 45 (Ethernet) Number of ports integrated switch Protocols PROFINET IO Controller PROFINET IO Device SIMATIC communication	10 bit Yes 625 μs Yes Yes Yes Yes Yes Yes Yes Y
Analog value generation for the inputs Integration and conversion time/resolution per channel Resolution with overrange (bit including sign), max. Integration time, parameterizable Conversion time (per channel) Encoder Connectable encoders 2-wire sensor Interface Isolated automatic detection of transmission rate Autonegotiation Autocrossing Interface types RJ 45 (Ethernet) Number of ports integrated switch Protocols PROFINET IO Controller PROFINET IO Device	10 bit Yes 625 μs Yes Yes Yes Yes Yes Yes Yes Y
Analog value generation for the inputs Integration and conversion time/resolution per channel Resolution with overrange (bit including sign), max. Integration time, parameterizable Conversion time (per channel) Encoder Connectable encoders 2-wire sensor Interface Isolated automatic detection of transmission rate Autonegotiation Autocrossing Interface types RJ 45 (Ethernet) Number of ports integrated switch Protocols PROFINET IO Controller PROFINET IO Device SIMATIC communication Open IE communication Web server	10 bit Yes 625 μs Yes Yes Yes Yes Yes Yes Yes Y
Analog value generation for the inputs Integration and conversion time/resolution per channel Resolution with overrange (bit including sign), max. Integration time, parameterizable Conversion time (per channel) Encoder Connectable encoders 2-wire sensor Interface Isolated automatic detection of transmission rate Autonegotiation Autocrossing Interface types RJ 45 (Ethernet) Number of ports integrated switch Protocols PROFINET IO Controller PROFINET IO Device SIMATIC communication Open IE communication Web server Media redundancy	10 bit Yes 625 μs Yes Yes Yes Yes Yes Yes Yes Y
Analog value generation for the inputs Integration and conversion time/resolution per channel Resolution with overrange (bit including sign), max. Integration time, parameterizable Conversion time (per channel) Encoder Connectable encoders 2-wire sensor Interface Isolated automatic detection of transmission rate Autonegotiation Autocrossing Interface types RJ 45 (Ethernet) Number of ports integrated switch Protocols PROFINET IO Controller PROFINET IO Device SIMATIC communication Open IE communication Web server Media redundancy PROFINET IO Controller	10 bit Yes 625 μs Yes Yes Yes Yes Yes Yes Yes Yes Yes Optionally also encrypted Yes No
Analog value generation for the inputs Integration and conversion time/resolution per channel Resolution with overrange (bit including sign), max. Integration time, parameterizable Conversion time (per channel) Encoder Connectable encoders 2-wire sensor Interface Isolated automatic detection of transmission rate Autonegotiation Autocrossing Interface types RJ 45 (Ethernet) Number of ports integrated switch Protocols PROFINET IO Controller PROFINET IO Device SIMATIC communication Open IE communication Web server Media redundancy PROFINET IO Controller Transmission rate, max.	10 bit Yes 625 μs Yes Yes Yes Yes Yes Yes Yes Y
Analog value generation for the inputs Integration and conversion time/resolution per channel Resolution with overrange (bit including sign), max. Integration time, parameterizable Conversion time (per channel) Encoder Connectable encoders 2-wire sensor Interface Isolated automatic detection of transmission rate Autonegotiation Autocrossing Interface types RJ 45 (Ethernet) Number of ports integrated switch Protocols PROFINET IO Controller PROFINET IO Device SIMATIC communication Open IE communication Web server Media redundancy PROFINET IO Controller	10 bit Yes 625 μs Yes Yes Yes Yes Yes Yes Yes Y

leaghrangus mada	No
— Isochronous mode	
— IRT	No
— PROFlenergy	No
— Prioritized startup	Yes
 Number of IO devices with prioritized startup, max. 	16
 Number of connectable IO Devices, max. 	16
 Number of connectable IO Devices for RT, 	16
max.	
— of which in line, max.	16
 Activation/deactivation of IO Devices 	Yes
Number of IO Devices that can be	8
simultaneously activated/deactivated, max.	
— Updating time	The minimum value of the update time also depends on the communication component set for PROFINET IO, on the number of IO devices and the quantity of configured user data.
PROFINET IO Device	
Services	
— PG/OP communication	Yes
— Isochronous mode	No
— IRT	No
— PROFlenergy	Yes
— Shared device	Yes
Number of IO Controllers with shared device.	2
max.	4
Protocols	
Supports protocol for PROFINET IO	Yes
PROFIBUS	Yes; CM 1243-5 (master) or CM 1242-5 (slave) required
AS-Interface	Yes; CM 1243-2 required
Protocols (Ethernet)	100, 011. 12.10 2.10441104
• TCP/IP	Yes
• DHCP	No
• SNMP	Yes
• DCP	Yes
• LLDP	Yes
Redundancy mode	103
Media redundancy	
— MRP	No
— MRPD	No
SIMATIC communication	110
• S7 routing	Yes
Open IE communication	103
TCP/IP	Yes
— Data length, max.	8 kbyte
 several passive connections per port, supported 	Yes
• ISO-on-TCP (RFC1006)	Yes
— Data length, max.	8 kbyte
• UDP	Yes
— Data length, max.	1 472 byte
Web server	
• supported	Yes
User-defined websites	Yes
OPC UA	
Runtime license required	Yes; "Basic" license required
OPC UA Server	Yes; Data access (read, write, subscribe), runtime license required
Application authentication	Available security policies: None, Basic128Rsa15, Basic256Rsa15,
Application authoritionton	Basic256Sha256
— User authentication	"anonymous" or by user name & password
 Number of sessions, max. 	5
•	

 Number of accessible variables, max. 	1 000
 Number of subscriptions per session, max. 	5
— Sampling interval, min.	100 ms
— Publishing interval, min.	200 ms
 Number of monitored items, max. 	500
 Number of server interfaces, max. 	2
 Number of nodes for user-defined server interfaces, max. 	1 000
Further protocols	
• MODBUS	Yes
Communication functions	
S7 communication	
• supported	Yes
• as server	Yes
• as client	Yes
User data per job, max.	See online help (S7 communication, user data size)
Number of connections	
overall	8 connections for open user communication (active or passive): TSEND_C, TRCV_C, TCON, TDISCON, TSEND and TRCV, 8 CPU/CPU connections (Client or Server) for GET/PUT data, 6 connections for dynamic assignment to GET/PUT or open user communication
Test commissioning functions	
Status/control	
Status/control variable	Yes
 Variables 	Inputs/outputs, memory bits, DBs, distributed I/Os, timers, counters
Forcing	
Forcing	Yes
Diagnostic buffer	
• present	Yes
Traces	
 Number of configurable Traces 	2
 Memory size per trace, max. 	512 kbyte
Interrupts/diagnostics/status information	
Diagnostics indication LED	
RUN/STOP LED	Yes
• ERROR LED	Yes
MAINT LED	Vac
	Yes
Integrated Functions	res
	Yes
Integrated Functions Frequency measurement controlled positioning	
Frequency measurement	Yes
Frequency measurement controlled positioning	Yes Yes
Frequency measurement controlled positioning Number of position-controlled positioning axes, max.	Yes Yes 8
Frequency measurement controlled positioning Number of position-controlled positioning axes, max. Number of positioning axes via pulse-direction interface	Yes Yes 8 4; With integrated outputs
Frequency measurement controlled positioning Number of position-controlled positioning axes, max. Number of positioning axes via pulse-direction interface PID controller	Yes Yes 8 4; With integrated outputs Yes
Frequency measurement controlled positioning Number of position-controlled positioning axes, max. Number of positioning axes via pulse-direction interface PID controller Number of alarm inputs	Yes Yes 8 4; With integrated outputs Yes 4
Frequency measurement controlled positioning Number of position-controlled positioning axes, max. Number of positioning axes via pulse-direction interface PID controller Number of alarm inputs Number of pulse outputs	Yes Yes 8 4; With integrated outputs Yes 4
Frequency measurement controlled positioning Number of position-controlled positioning axes, max. Number of positioning axes via pulse-direction interface PID controller Number of alarm inputs Number of pulse outputs Limit frequency (pulse)	Yes Yes 8 4; With integrated outputs Yes 4
Frequency measurement controlled positioning Number of position-controlled positioning axes, max. Number of positioning axes via pulse-direction interface PID controller Number of alarm inputs Number of pulse outputs Limit frequency (pulse) Potential separation	Yes Yes 8 4; With integrated outputs Yes 4
Frequency measurement controlled positioning Number of position-controlled positioning axes, max. Number of positioning axes via pulse-direction interface PID controller Number of alarm inputs Number of pulse outputs Limit frequency (pulse) Potential separation Potential separation digital inputs	Yes Yes 8 4; With integrated outputs Yes 4 100 kHz
Frequency measurement controlled positioning Number of position-controlled positioning axes, max. Number of positioning axes via pulse-direction interface PID controller Number of alarm inputs Number of pulse outputs Limit frequency (pulse) Potential separation Potential separation digital inputs • Potential separation digital inputs	Yes Yes 8 4; With integrated outputs Yes 4 100 kHz
Frequency measurement controlled positioning Number of position-controlled positioning axes, max. Number of positioning axes via pulse-direction interface PID controller Number of alarm inputs Number of pulse outputs Limit frequency (pulse) Potential separation Potential separation digital inputs • Potential separation digital inputs • between the channels, in groups of	Yes Yes 8 4; With integrated outputs Yes 4 100 kHz
Frequency measurement controlled positioning Number of position-controlled positioning axes, max. Number of positioning axes via pulse-direction interface PID controller Number of alarm inputs Number of pulse outputs Limit frequency (pulse) Potential separation Potential separation digital inputs • Potential separation digital inputs • between the channels, in groups of Potential separation digital outputs	Yes Yes 8 4; With integrated outputs Yes 4 4 100 kHz
Frequency measurement controlled positioning Number of position-controlled positioning axes, max. Number of positioning axes via pulse-direction interface PID controller Number of alarm inputs Number of pulse outputs Limit frequency (pulse) Potential separation Potential separation digital inputs • Potential separation digital inputs • between the channels, in groups of Potential separation digital outputs • Potential separation digital outputs	Yes Yes 8 4; With integrated outputs Yes 4 100 kHz No 1
Frequency measurement controlled positioning Number of position-controlled positioning axes, max. Number of positioning axes via pulse-direction interface PID controller Number of alarm inputs Number of pulse outputs Limit frequency (pulse) Potential separation Potential separation digital inputs • Potential separation digital inputs • between the channels, in groups of Potential separation digital outputs • Potential separation digital outputs	Yes Yes 8 4; With integrated outputs Yes 4 100 kHz No 1 Yes No
Frequency measurement controlled positioning Number of position-controlled positioning axes, max. Number of positioning axes via pulse-direction interface PID controller Number of alarm inputs Number of pulse outputs Limit frequency (pulse) Potential separation Potential separation digital inputs • Potential separation digital inputs • between the channels, in groups of Potential separation digital outputs • Potential separation digital outputs • between the channels • between the channels • between the channels, in groups of	Yes Yes 8 4; With integrated outputs Yes 4 100 kHz No 1 Yes No
Frequency measurement controlled positioning Number of position-controlled positioning axes, max. Number of positioning axes via pulse-direction interface PID controller Number of alarm inputs Number of pulse outputs Limit frequency (pulse) Potential separation Potential separation digital inputs • Potential separation digital inputs • between the channels, in groups of Potential separation digital outputs • Potential separation digital outputs • between the channels • between the channels, in groups of	Yes Yes 8 4; With integrated outputs Yes 4 100 kHz No 1 Yes No

 Test voltage at air discharge 	8 kV
Test voltage at contact discharge	6 kV
Interference immunity to cable-borne interference	
 Interference immunity on supply lines acc. to IEC 61000-4-4 	Yes
 Interference immunity on signal cables acc. to IEC 61000-4-4 	Yes
Interference immunity against voltage surge	
 Interference immunity on supply lines acc. to IEC 61000-4-5 	Yes
Interference immunity against conducted variable disturbance	e induced by high-frequency fields
 Interference immunity against high-frequency radiation acc. to IEC 61000-4-6 	Yes
Emission of radio interference acc. to EN 55 011	
Limit class A, for use in industrial areas	Yes; Group 1
Limit class B, for use in residential areas	Yes; When appropriate measures are used to ensure compliance with the limits for Class B according to EN 55011
Standards, approvals, certificates	and minutes and a state of the
CE mark	Yes
	Yes
UL approval	
cULus	Yes
FM approval	Yes
RCM (formerly C-TICK)	Yes
KC approval	Yes
Marine approval	Yes
Ambient conditions	
Free fall	
• Fall height, max.	0.3 m; five times, in product package
Ambient temperature during operation	
• min.	-20 °C
• max.	60 °C; Number of simultaneously activated inputs or outputs 4 or 3 (no adjacent points) at 60 °C horizontal or 50 °C vertical, 8 or 6 at 55 °C horizontal or 45 °C vertical
 horizontal installation, min. 	-20 °C
 horizontal installation, max. 	60 °C
 vertical installation, min. 	-20 °C
 vertical installation, max. 	50 °C
Ambient temperature during storage/transportation	
• min.	-40 °C
• max.	70 °C
Air pressure acc. to IEC 60068-2-13	
Operation, min.	795 hPa
Operation, max.	1 080 hPa
•	660 hPa
Storage/transport, min. Storage/transport, may	
Storage/transport, max. Altitude during expression relating to acceleve.	1 080 hPa
Altitude during operation relating to sea level	4.000
Installation altitude, min.	-1 000 m
Installation altitude, max.	2 000 m
Relative humidity	
Operation, max.	95 %; no condensation
Vibrations	
 Vibration resistance during operation acc. to IEC 60068-2-6 	2 g (m/s²) wall mounting, 1 g (m/s²) DIN rail
Operation, tested according to IEC 60068-2-6	Yes
Shock testing	
• tested according to IEC 60068-2-27	Yes; IEC 68, Part 2-27 half-sine: strength of the shock 15 g (peak value), duration 11 ms
Pollutant concentrations	
 SO2 at RH < 60% without condensation 	S02: < 0.5 ppm; H2S: < 0.1 ppm; RH < 60% condensation-free
Configuration	

Programming	
Programming language	
— LAD	Yes
— FBD	Yes
SCL	Yes
Know-how protection	
 User program protection/password protection 	Yes
 Copy protection 	Yes
Block protection	Yes
Access protection	
 Protection level: Write protection 	Yes
 Protection level: Read/write protection 	Yes
Protection level: Complete protection	Yes
Cycle time monitoring	
adjustable	Yes
Dimensions	
Width	90 mm
Height	100 mm
Depth	75 mm
Weights	
Weight, approx.	370 g

3/2/2021

last modified: